# Statistic on Manifolds On boundary detection

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Seminario de Probabilidad y Estadística - CMAT

1 Manifold estimation - Topological data analysis

## 2 Some problems and models





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On boundary estimation



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# Densities on Manifolds.

**General assumption:**  $\mathcal{M} \subset \mathbb{R}^d$  is a  $\mathbb{C}^\infty$ , compact, *d'*-dimensional manifold, with the metric inherit from  $\mathbb{R}^d$ .

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#### Densities on manifolds.

Let *P* a probability on  $\mathcal{B}(\mathcal{M})$ , a random variable on  $\mathcal{M}$  is a measurable function  $X : \Omega \to \mathcal{M}$ . If  $\mathcal{M}$  is orientable a density is  $f : \mathcal{M} \to \mathbb{R}^+$  which fulfils,

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## In local coordinates

$$\int_{U} f dv = \int_{\varphi(U)} f(\varphi^{-1}(x)) \sqrt{\det g_{ij}(\varphi^{-1}(x))} dx$$

where  $g_{ij}$  are the coefficients of the metric g in the local coordinates  $(U, \varphi)$ .

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# Variance and Expectation

#### Variance

Let  $y \in \mathcal{M}$ , and X a r.v on  $\mathcal{M}$  with density f, the variance on y,  $\sigma_X(y)^2$  is

 $\mathbb{E}(d(y,X)^2) = \int_{\mathcal{M}} d(y,z)^2 f(z) dv(z)$  being *d* the geodesic distance.

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$$\mathbb{E}(d(y,X)^2) = \int_{\mathcal{M}} d(y,z)^2 f(z) dv(z) \quad \text{being } d \text{ the geodesic distance}$$

#### Expectation

If  $\sigma_X(y)^2 < \infty$  for all y, the set (possibly empty) of expectations is

$$\mathbb{E}(X) = \operatorname{argmin}_{y \in \mathcal{M}} \sigma_X(y)^2.$$

*Kendall, 1990:* if  $supp(f) \subset B_d(x, r)$  for some regular geodesic ball that does not meet the cutlocus of *x*, exists a unique  $\mathbb{E}(X)$ .

Manifold estimation - Topological data analysis

## 2 Some problems and models

On boundary estimation



# Manifold Recovery from a sample of points, filament model

The filament model:  $X_i = f(U_i) + Z_i$ , where  $f : [0, 1] \to \mathbb{R}^d$ , the  $U_i$  are uniform and the  $Z_i$  are zero-mean compact supported; Genovese et al. (2012a).

**INPUT:**  $\hat{S}$  and  $\hat{\partial S}$  D.W. of radius  $\varepsilon > 0$ . **OUTPUT:**  $\hat{\Gamma}$ .

## ALGORITHM:

1) Compute 
$$\hat{\Delta}(y) = d(y, \partial \hat{S})$$
 for all  $y \in \hat{S}$ .  
2)  $\hat{\sigma} = \max_{y \in \hat{S}} \hat{\Delta}(y)$ 

3) 
$$\delta = 2\varepsilon, \hat{\Gamma} = \{ y \in \hat{S} : d(y, \partial \hat{S}) \ge \hat{\sigma} - \delta \}$$



FIG 6. These plots illustrate the EDT-based estimator. Left: filament and data. Center: Estimated boundary. Right: EDT estimator  $\widehat{\Gamma}$ .

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# Inference on the dimension:

## Testing the manifold hypothesis, Fefferman et al 2015

 $\mathfrak{G}(d, V, \tau)$ : *d* dimensional  $\mathbb{C}^2$  submanifolds of the unit ball in  $\mathcal{H}$  a separable Hilbert space, with volume  $\leq V$  and reach  $\leq \tau < 1$ . *P* a probability with support B(0, 1). **The problem:** decide from a sample of *P* if there exists  $\mathcal{M} \in \mathfrak{G}(d, CV, \tau/C)$  such that

$$\int d(M,x)^2 dP(x) < C\varepsilon$$

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### Finding the Homology of Submanifolds, Smale et al 2008

**Theorem:** Let  $\mathcal{M} \subset \mathbb{R}^n$  compact with reach  $\tau$ .  $\aleph_n = X_1, \ldots, X_n$  iid uniform on  $\mathcal{M}$ . Let  $0 < \varepsilon < \tau/2$  and  $U = \bigcup_i B(X_i, \varepsilon)$ . Then for  $n = n(\delta)$ , with probability greater than the homology of U equals the homology of  $\mathcal{M}$  with probability >  $1 - \delta$ .

# Estimation of the dimension:

## MLE of Intrinsic Dimension, Bickel and Levina 2005

**Heuristic:**  $X_1, \ldots, X_n$  iid in  $\mathbb{R}^p$ ,  $X_i = g(Y_i)$  where  $Y_i$  are sampled from a unknown density f on  $\mathbb{R}^m$  and  $f(x) \sim \text{constant on } B(x, R)$  for some R, with  $m \leq p$  and g is *smooth*. If we consider the process

$$N(t,x) = \sum_{i=1}^{n} \mathbb{I}_{\{X_i \in B(x,t)\}} \sim Poisson(\lambda(t)) \quad 0 \le t \le R,$$

with  $\lambda(t) = f(x) Vol(B_m(0, 1))mt^{m-1}$ . If  $\theta = \log(f(x))$ , the log-likelihood of N(t) is

$$L(m,\theta) = \int_0^R \log(\lambda(t)) dN(t) - \int_0^R \lambda(t) dt,$$

then the MLE for *m* is  $\hat{m}_k(x) = \left[\frac{1}{k-1}\sum_{j=1}^{k-1}\log\frac{d(x, X_k(x))}{d(x, X_j(x))}\right]^{-1}$ .

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• *Noiseless model*: the data  $X_1, \ldots, X_n$  are taken from a distribution whose support is the manifold  $\mathcal{M}$ ; Aamari and Levrard (2015), Amenta et al. (2002).



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- *The parallel model*: The  $X_i$  have a distribution whose support is the parallel set  $B(\mathcal{M}, r)$ ; Berrendero et al. (2014).

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# Open problems

- Things to define:
  - depths.
  - outlier.
  - classical distributions.
- To estimate/test:
  - Positive reach/condition number
  - Is M orientable?
  - It has empty interior? In general, detect a lower (non-linear) dimensional structure.
  - Estimate  $\mu_{d'}(\partial M)$  being  $\mu_{d'}$  de d' Lebesgue measure.

Manifold estimation - Topological data analysis

Some problems and models

③ On boundary estimation

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## Model and problem

## The model and the problem

We will assume the noisless model wit  $f > f_0 > 0$  Lipschitz. The problem

 $\left\{ \begin{array}{ll} H_0: & \partial M = \emptyset \\ H_1: & \partial M \neq \emptyset \end{array} \right.$ 

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### Why not just estimate the manifold?

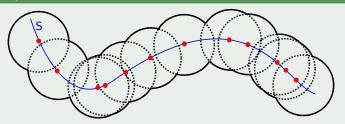


Figure: The boundary of D.W. estimator is not a good estimation of  $\partial M$ 

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# The heuristic idea

$$\mathfrak{X}_{k_n,x} = \{X_{1(x)}, \dots, X_{k_n(x)}\}; r_{x,n} = \max_{y \in \mathfrak{X}_{k_n,x}} \|y - x\|; \overline{X}_{x,k_n} = \frac{1}{k_n} \sum_{k=1}^{k_n} X_{k(x)}.$$
  
Assume that  $k_n \to +\infty$  slowly enough to have  $\max_{x \in S} r_{x,n} \stackrel{a.s.}{\to} 0.$ 

## If $\partial M = \emptyset$

 $\{ (X_{1(x)} - x)/r_{x,n} \dots (X_{k_n(x)} - x)/r_{x,n} \} \text{ is "close" to a sample uniformly} \\ \text{distributed on } B(x, 1) \subset \mathbb{R}^{d'} \text{ with } d' = dim(\mathcal{M}). \\ \text{As } k_n \to \infty \text{ we expect } \|\overline{X}_{x,k_n} - x\| \stackrel{a.s.}{\to} 0, \text{ then } \max_i \|\overline{X}_{x_i,k_n} - x\| \stackrel{a.s.}{\to} 0.$ 

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### If $\partial M$ is a $\mathbb{C}^2$ manifold

If  $x \in \partial M$ , the "locally rescaled sample" is close to sample on a half unit ball and  $\|\overline{X}_{x,k_n} - x\| \to \alpha_{d'}$  with  $\alpha_{d'}$  a positive constant. Then  $\max_i \|\overline{X}_{X_i,k_n} - x\| \xrightarrow{a.s.} \alpha_{d'}$ .

We decide  $\partial M = \emptyset$  if  $\max_i \|\overline{X}_{X_i,k_n} - x\|$  is small enough.

# Some definitions.

#### Definition

Let us define:  $r_{i,k_n} = ||X_i - X_{k_n(i)}||$ ;  $r_n = \max_{i \le n} r_{i,k_n}$ 

$$\mathfrak{X}_{i,k_n} = egin{pmatrix} X_{1(i)} - X_i \ dots \ X_{k_n(i)} - X_i \end{pmatrix}; \quad \hat{S}_{i,k_n} = rac{1}{k_n} (\mathfrak{X}_{i,k_n})' (\mathfrak{X}_{i,k_n}).$$

•  $Q_{i,k_n}$  is the plane spanned by the d' eigenvectors of  $\hat{S}_{i,k_n}$  associated to the d' largest eigenvalues.

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- $Q_{i,k_n}$  is the plane spanned by the d' eigenvectors of  $\hat{S}_{i,k_n}$  associated to the d' largest eigenvalues.
- $X_{k(i)}^*$  the normal projection of  $X_{k(i)} X_i$  on  $Q_{i,k_n}$  and  $\overline{X}_{k_n,i} = \frac{1}{k_n} \sum_{j=1}^{k_n} X_{j(i)}^*$ .

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• 
$$\delta_{i,k_n} = \frac{(d'+2)k_n}{r_{i,k_n}^2} \|\overline{X}_{k_n,i}\|^2$$
, for  $i = 1, \dots, n$ .

The proposed test statistic is:  $\Delta_{n,k_n} = \max_i \delta_{i,k_n}$ .

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Some problems and model

## Some results

We will denote by  $\Psi_{d'}(t)$  the cumulative distribution function of a  $\chi^2(d')$  distribution and  $F_{d'}(t) = 1 - \Psi_{d'}(t)$ .

#### Theorem

 $\mathfrak{M}$  is  $\mathbb{C}^2$ , compact, the density f is Lipschitz and  $f(x) > f_0$  on  $\mathfrak{M}$ .  $\partial \mathfrak{M} = \emptyset$  or  $\mathbb{C}^2$ . If  $k_n/(\ln(n))^4 \to \infty$  and  $(\ln(n))k_n^{1+d'}/n \to 0$ , the test

$$\begin{cases} H_0: & \partial M = \emptyset \\ H_1: & \partial M \neq \emptyset \end{cases}$$
(1)

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with the rejection zone

$$W_n = \left\{ \Delta_{n,k_n} \ge F_{d'}^{-1}(9\alpha/(2e^3n)) \right\},\tag{2}$$

*fulfills:*  $\mathbb{P}_{H_0}(W_n) \leq \alpha + o(1)$ . The test (1) with rejection zone (2) has power 1 for n large enough.

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# More Results

#### Theorem

Under previous conditions, if we define

$$\hat{\Psi}_{n,k_n}(x) = \frac{1}{n} \sum_{i=1}^n \mathbb{I}_{\{\delta_{i,k_n} \leq x\}},$$

then, for all  $x \in M$ ,

$$\mathbb{E}\big(\hat{\Psi}_{n,k_n}(x)-\Psi_{d'}(x)\big)^2\to 0 \quad \text{as } n\to\infty.$$

# Some probabilistic results for the proof

#### Lemma

Let  $X_1, \ldots, X_n$  be an i.i.d. sample uniformly on  $\mathcal{B}(x, r) \subset \mathbb{R}^d$ . Let us denote  $\overline{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$ , then we have:

$$\frac{(d+2)n\|\overline{X}_n - x\|^2}{r^2} \xrightarrow{\mathcal{L}} \chi^2(d), \tag{3}$$

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(3)

#### Lemma

Let X be uniformly distributed on  $\mathcal{B}_u(x,r) = \mathcal{B}(x,r) \cap \{z \in \mathbb{R}^d : \langle z - x, u \rangle \ge 0\}$  where u is a unit vector, then

$$\mathbb{E}\left(\frac{\langle X-x,u\rangle}{r}\right) = \alpha_d, \text{ where } \alpha_d = \left(\frac{\Gamma(\frac{d+2}{2})}{\sqrt{\pi}\Gamma(\frac{d+3}{2})}\right). \tag{4}$$

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# Some key results for the proofs

#### Theorem

Let  $\mathcal{M} \subset \mathbb{R}^d$  be a compact, d'-dimensional  $\mathfrak{C}^2$  manifold without boundary. X with Lipschitz density f. There exist positive constants  $R_1$  and  $C_1$  such that: if  $r \leq R_1$ , then  $|\mathbb{P}_X(\mathfrak{B}(x,r)) - f(x)\sigma_{d'}r^{d'}| \leq C_1r^{d'+1}$ , with  $\sigma_{d'} = vol(\mathfrak{B}_d(0,1))$ 

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#### Lemm<u>a</u>

Let  $X_1, \ldots, X_n$  be an i.i.d. of  $\mathbb{P}_X$ , with  $\partial \mathcal{M} = \emptyset$ . Then there exists a constant  $A_d$  such that

$$X^*_{k_n(i)} = (I_d + E_{i,n})\varphi_{X_i}(X_{k_n(i)}) - X_i \text{ with: } \max_i \|E_{i,n}\|_{\infty} \le A_d \sqrt{\frac{\ln(n)}{k_n}} \text{ e.a.s.}$$

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# Simulations

S2+ boundary points

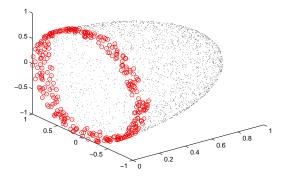


Figure: n = 3000 points,  $X_i$ , boundary point if  $\frac{2e^3}{9}F_{d'}(\delta_{i,k}) \le 5\%$ 

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# Simulations 8 1



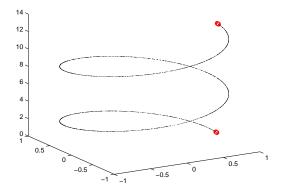


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# Simulations

moebus ring boundary points

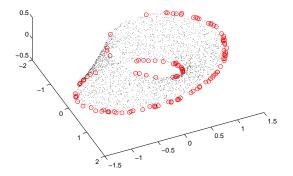


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